- 1. The equation of motion is $m\dot{\mathbf{v}} = q [\mathbf{v} \times \mathbf{B} + \mathbf{E}]$, where q = -e and $\mathbf{E} = E_0 \hat{\mathbf{x}}$.
 - (a) At time t = 0 the particle is at rest. Hence it is first accelerated in the direction antiparallel to the electric field **E** (anti-parallel because of the negative charge), because the $\mathbf{v} \times \mathbf{B}$ term is zero. Once it starts to move the first term can have an effect. If $\mathbf{v} \times \mathbf{B} = 0$ the magnetic field will have no effect and the particle will continue to move antiparallel to **E**. This will be the case for **B** parallel (or anti-parallel) to **E**.



(b) The electric field will accelerate the particle in the $-\hat{i}$, anti-parallel to the x direction. If the magnetic field is parallel or anti-parallel to the z-axis, $\mathbf{B} = \pm B_0 \hat{k}$, then by the right hand rule the motion will only be in the x - y plane. We must choose the sign of \mathbf{B} so that, once the particle moves, it moves in the positive y direction, $+\hat{j}$. After a small time dt the velocity will be

$$\mathbf{v} = -\frac{1}{m} e E_0 \, dt \widehat{\boldsymbol{i}}.$$

For $\mathbf{B} = B_0 \hat{k}$ the acceleration due to the magnetic field will be

$$q\mathbf{v} \times \mathbf{B} = \frac{1}{m}(-e)(-eE_0dt)\widehat{\mathbf{i}} \times (B_0\widehat{\mathbf{k}}) = \frac{1}{m}e^2E_0B_0\,dt\widehat{\mathbf{i}} \times \widehat{\mathbf{k}} = -\frac{1}{m}e^2E_0B_0\widehat{\mathbf{j}}.$$

This is the negative y direction. Hence we need $\mathbf{B} = -B_0 \hat{k}$, in the negative z direction, to have motion in the x - y plane with y > 0.



- 2.
- (a) $|\mathbf{r}| = k$. This is a sphere with radius k.
- (b) $\mathbf{r} \cdot \hat{\mathbf{k}} = \ell$, where $\hat{\mathbf{k}}$ is the unit vector along the z-axis. This is an infinite plane parallel to the x - y plane, a distance ℓ from the origin in the z direction.
- (c) $\mathbf{r} \cdot \hat{\mathbf{k}} = m |\mathbf{r}|$. From the definition of the scalar product, $\mathbf{r} \cdot \hat{\mathbf{k}} = |r| \cos \theta$, where θ is the angle with respect to the z axis. Hence the surface is all points that lie at the angle $\theta = \arccos(m)$; *i. e.* a cone.
- (d) $|\mathbf{r} (\mathbf{r} \cdot \mathbf{k})\mathbf{k}| = n$. This is the set of points such that the magnitude of the vector $\mathbf{r} - (\mathbf{r} \cdot \mathbf{\hat{k}})\mathbf{\hat{k}}$ is a constant. What is this vector? It is obtained by subtracting from \mathbf{r} the portion of the vector that is parallel to the z axis. Recall that we can resolve

$$\mathbf{r} = A\hat{k} + \mathbf{B},$$

where $A = \mathbf{r} \cdot \hat{\mathbf{k}}$ and **B** is orthogonal to $\hat{\mathbf{k}}$, and is in fact the vector we are looking for. Hence (see figure) the desired surface is the surface of a cylinder of radius n.



3. To show that the set of vectors (1, 0, 1), (1, 1, 0), and (1, -3, 4) lie on a line, we must examine the differences between them. For example,

(1,0,1) - (1,1,0) = (0,-1,1)(1,0,1) - (1,-3,4) = (0,3,-3)(1,1,0) - (1,-3,4) = (0,4,-4).

The difference between any two of them is a scalar multiple of the same vector, (0, 1, -1). Hence they can be reached by moving parallel to a single vector, and they lie on a straight line.

The equation of the line can be given as $\mathbf{r} = \mathbf{a} + \lambda \mathbf{b}$, where λ is the independent variable parametrizing points on the line. \mathbf{a} is any point on the line, and \mathbf{b} is the direction one must travel to reach other points on the line. We can choose $\mathbf{b} = (0, 1, -1)$ (or any scalar multiple), and \mathbf{a} any of the points we are given. Hence the following are all equivalent representations of the line:



$$\begin{aligned} \mathbf{r} &= (1,0,1) + \lambda(0,1,-1) \\ \mathbf{r} &= (1,1,0) + \lambda(0,1,-1) \\ \mathbf{r} &= (1,-3,4) + \lambda(0,1,-1). \end{aligned}$$